

Tentamen
SOLID MECHANICS (NASM)
April 18, 2011, 14:00–17:00 h

Question 1

- a. According to Mohr's circle, the three principal stresses $\sigma_1 > \sigma_2 > \sigma_3$ define three maximum shear stresses τ_1, τ_2, τ_3 in planes at 45° relative to subsequent sets of three principal stress directions. Can the hydrostatic stress be computed from these maximum shear stresses?
- b. Show that in the geometrically linear theory, the deformation gradient F_{ij} can be expressed as

$$F_{ij} = \delta_{ij} + \varepsilon_{ij}$$

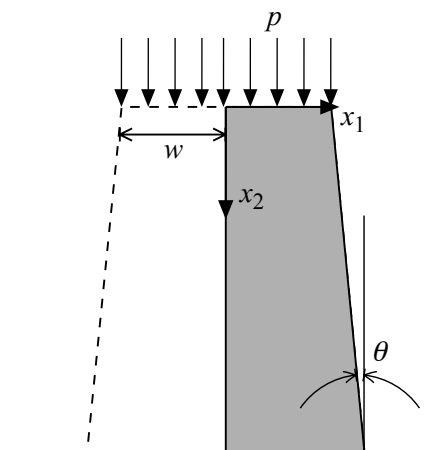
in case there are no rotations.

- c. Consider the planar deformation field specified by the strain components

$$[\varepsilon_{\alpha\beta}] = \begin{bmatrix} \varepsilon_1 & 0 \\ 0 & \varepsilon_2 \end{bmatrix},$$

but first draw a unit circle, $X_1^2 + X_2^2 = 1$, onto the material. Taking into consideration that $dx_i = F_{ij}dX_j$ also applies to finite length elements when F_{ij} is uniform (as in this question), determine the shape of the square after the above strain has been applied.

Question 2 A long ridge is cut out of a single crystal by means of focused ion beam milling. Because of this process the sides of the ridge are not perfectly vertical but have a small taper angle θ . The properties of the crystal are tested by subjecting the top to a pressure, p , which is assumed to be uniformly distributed over the top width w . Since the ridge is long, we can also assume that it deforms in plane strain perpendicular to the x_1 - x_2 plane shown. Because of symmetry only half of the cross-section (the gray area) needs to be analyzed.



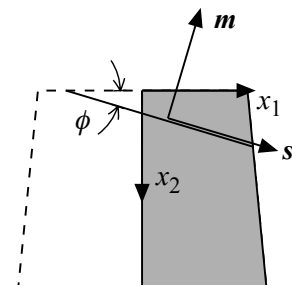
- a. Specify the boundary conditions for the left and the right-hand side of the gray region in terms of stress components.
- b. Assuming the vertical stress σ_{22} to be uniform in x_1 , determine the value at arbitrary depth x_2 .

- c. Use equilibrium to find the differential equation for the shear stress σ_{12} in terms of σ_{22} . Solve this equation, taking into account the appropriate boundary conditions, and prove that the stress field satisfies

$$\frac{\sigma_{12}}{\sigma_{22}} = \frac{\xi_1}{1 + \xi_2}, \quad \text{with } \xi_1 := (x_1/w) \tan \theta, \xi_2 := (x_2/w) \tan \theta$$

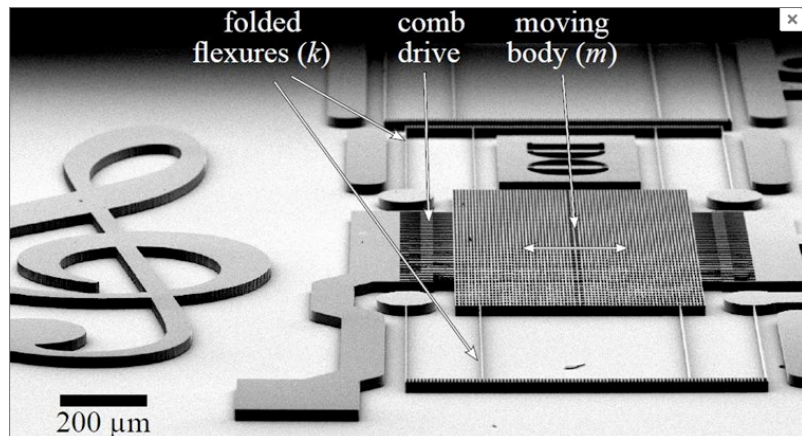
- d. Similarly, find the differential equation for the shear stress σ_{11} in terms of σ_{12} . Solve this equation, taking into account the appropriate boundary conditions, and prove that σ_{11} varies quadratically with x_1 .

- e. Let the orientation of the slip plane normal m and the slip direction s of a slip system in the crystal be determined by the angle φ as indicated in this figure. At which location will slip initiate?



Question 3

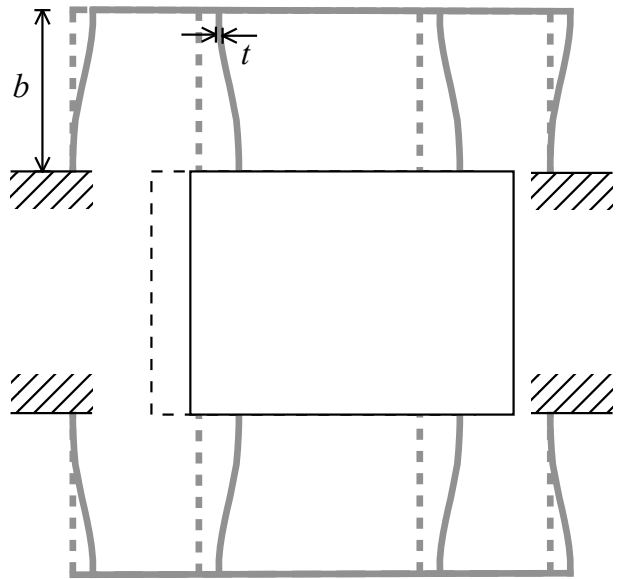
A group of nanotechnology students from Twente University has recently presented a musical instrument called “micronium”. It is special because it is able, by mechanical means, to produce tones with audible frequencies, despite the fact that the vibrating mass weighs only a few dozen micrograms. This is



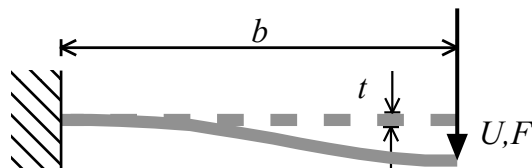
non-trivial in view of the well-known formula $f = \sqrt{k/m}/(2\pi)$ for the eigenfrequency of a mass (m)–spring system (stiffness k): at small scales, the mass m is necessarily small so that the stiffness needs to be small in order to keep f in the audible range (~ 20 – 20.000 Hz). The amplitude of the vibrations is only a few micrometers. The device has a separate unit for each tone; a scanning electron microscopy image of one unit is shown in the figure above. It consists of a thin rectangular plate that is mounted in between spring structures at the top and the bottom

consisting of thin slender beams (the comb structures on the left and the right-hand side serve to actuate ('pluck') the mass-spring system and as a sensor to pick up of the frequency, which is then sent to an amplifier).

The figure on the right-hand side shows a mechanical model, comprising four interconnected leaf springs on top and bottom, having length b and width t (the thickness of the springs and the rectangular mass are the same). Both the equilibrium position (dashed lines) and a deflected configuration are shown (the outer leaf springs are mounted on posts fixed to the wafer).



- a. First determine the stiffness F/U of a single leaf spring against a sideways displacement U , see figure below (this can be done either by solving the differential beam equation (3.49) plus appropriate boundary conditions or by combining the vergeet-me-nietjes of Fig. 3.6 in a clever way).



- b. Denoting the stiffness determined above by k_1 , compute the total stiffness k of the spring system in a micronium unit.
- c. Using values of Young's modulus $E = 112\text{GPa}$ and mass density $\rho = 2.3\text{g/cm}^3$ for silicon, estimate the thickness t of the springs in order that the frequency of the tone produced by the micronium unit is 1000Hz . Note: from the micrograph at the start of this question, one could derive that $b = 200\ \mu\text{m}$ and that the moving mass has an area of $500 \times 600 = 30 \times 10^4\ \mu\text{m}^2$.



Question	# points
1	1.5
2	4.5
3	3.0

Grade = # points + 1

①

a) $\tau_1 = \frac{1}{2}(\sigma_1 - \sigma_2), \dots$ etc.

the τ 's are defined by differences of principal stresses \rightarrow principal stresses σ_i 's cannot be computed from τ_i 's \rightarrow cannot compute

$$\sigma_m = \frac{1}{3}(\sigma_1 + \sigma_2 + \sigma_3) \text{ from } \tau_i \text{'s}$$

b) geometrically linear theory: $\epsilon_{ij} = \frac{1}{2}(u_{i,j} + u_{j,i})$
no rotations: $\omega_{ij} = \frac{1}{2}(u_{i,j} - u_{j,i}) = 0$

$$\Rightarrow \epsilon_{ij} = u_{i,j}$$

$$\Rightarrow F_{ij} = \delta_{ij} + u_{i,j} = \delta_{ij} + \epsilon_{ij}$$

c) uniform F_{ij} means that all points (X_1, X_2) move to (x_1, x_2) given by $x_i = F_{ij} X_j$, that is

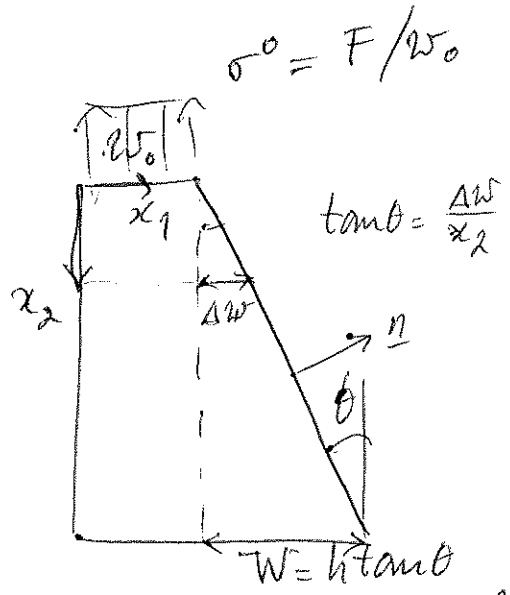
$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1+F_{11} & 0 \\ 0 & 1+F_{22} \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} = \begin{pmatrix} 1+\epsilon_{11} & 0 \\ 0 & 1+\epsilon_{22} \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix}$$

Points (X_1, X_2) on circle

$$X_1^2 + X_2^2 = \left(\frac{x_1}{1+\epsilon_1}\right)^2 + \left(\frac{x_2}{1+\epsilon_2}\right)^2 = 1$$

defines ellipse with axes of length $1+\epsilon_1$ and $1+\epsilon_2$ in x_1 and x_2 direction, respectively.

②



$$w(x_2) = w_0 + \Delta w$$

$$= w_0 + x_2 \tan \theta$$

$$\sigma_{22}(x_2) = \frac{F}{w(x_2)} = \frac{F}{w_0(1 + x_2/w_0 t)}$$

$$= \frac{\sigma^0}{1 + \frac{x_2 t}{w_0}}$$

$$\sigma_{22,2} = -\sigma^0 \left(1 + \frac{x_2 t}{w_0}\right)^{-2} t/w_0$$

$$= -\frac{t/w_0}{\left(1 + \frac{x_2 t}{w_0}\right)} \sigma_{22}$$

$$\sigma_{12,1} + \sigma_{22,2} = 0 \Rightarrow \sigma_{12,1} = -\sigma_{22,2} = \sigma_{22} \frac{t/w_0}{1 + \frac{x_2 t}{w_0}}$$

$$\Rightarrow \sigma_{12} = \sigma_{22} \left(\frac{\frac{x_1 t}{w_0}}{1 + \frac{x_2 t}{w_0}} \right) + C$$

$$n = \begin{pmatrix} C \\ -S \end{pmatrix} \Rightarrow \begin{pmatrix} \sigma_{11} C - \sigma_{12} S \\ \sigma_{12} C - \sigma_{22} S \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ at } \begin{matrix} x_1 = w_0 + x_2 t \\ = w_0 \left(1 + \frac{x_2 t}{w_0}\right) \end{matrix}, x_2$$

$$\sigma_{12} - \sigma_{22} t = \sigma_{22} \frac{\left(1 + \frac{x_2 t}{w_0}\right) t}{1 + \frac{x_2 t}{w_0}} + 0 - \sigma_{22} t = \underline{C = 0} \quad \checkmark$$

$$\Rightarrow \sigma_{12}(x_1=0) = C = 0 \quad \checkmark$$

$$\frac{\sigma_{12}}{\sigma_0} = \frac{\left(\frac{x_1}{w}\right) t}{\left[1 + \left(\frac{x_2}{w}\right) t\right]^2}$$

$$\sigma_{11,1} + \sigma_{12,2} = 0$$

$$\sigma_{11,1} = -\sigma_{12,2} = - \left\{ \sigma_{22,2} \frac{\frac{x_1 t}{w}}{1 + \frac{x_2 t}{w}} - \sigma_{22} \frac{\frac{x_1 t}{w} \frac{1}{w_0} t}{\left[1 + \frac{x_2 t}{w}\right]^2} \right\}$$

$$= +\sigma_{22} \left\{ \frac{t/w_0 \frac{x_1 t}{w}}{\left[1 + \frac{x_2 t}{w}\right]^2} + \frac{\frac{x_1 t}{w} \frac{1}{w} t}{\left[\quad \right]^2} \right\}$$

$$= 2 \sigma_{22} \frac{\frac{x_1 t}{w} \frac{t}{w}}{\left[1 + \frac{x_2 t}{w}\right]^2}$$

$$\sigma_{11} = \sigma_{22} \frac{\frac{x_1^2}{w^2} t^2}{\left[1 + \frac{x_2 t}{w}\right]^2} + C_2$$

$$= \sigma_{12} \left(\frac{\frac{x_1 t}{w}}{1 + \frac{x_2 t}{w}} \right) + C_2$$

at $(x_1 = w_0(1 + \frac{x_2}{w_0} t), x_2)$: $\sigma_{11} = \sigma_{12} \tan \theta \Rightarrow$

$$\sigma_{12} \frac{\cancel{\left(1 + \frac{x_2}{w_0} t\right)} t}{\cancel{\left(1 + \frac{x_2}{w_0} t\right)}} = (\sigma_{12} \cancel{t} + C_2) t \Rightarrow C_2 = 0.$$

$$\frac{\sigma_{11}}{\sigma_0} = \frac{\left(\frac{x_1}{w}\right)^2 \frac{t^2}{\tan}}{\left[1 + \frac{x_2 t}{w}\right]^3}$$

$$\tau = \sigma_{ij} P_{ij} = m_i \sigma_{ij} s_j$$

$$[m_i] = \begin{pmatrix} \sin \varphi \\ -\cos \varphi \end{pmatrix} \quad [s_i] = \begin{pmatrix} \cos \varphi \\ +\sin \varphi \end{pmatrix}$$

$$\tau = (s \ -c) \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{12} & \sigma_{22} \end{pmatrix} \begin{pmatrix} c \\ s \end{pmatrix}$$

$$= \frac{1}{2} (\sigma_{11} - \sigma_{22}) \sin 2\varphi - \sigma_{12} \cos 2\varphi$$

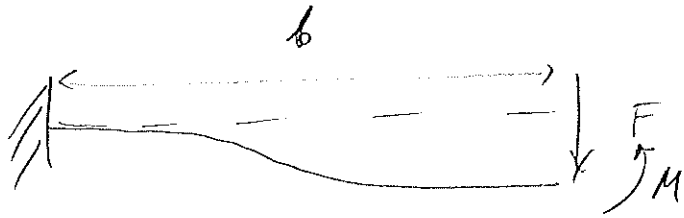
All σ_{ij} largest at $x_2 = 0$: ξ_1

$$\frac{\sigma_{11}}{\sigma_0} = \left(\frac{x_1}{w} t \right)^2, \quad \frac{\sigma_{12}}{\sigma_0} = \left(\frac{x_1}{w} t \right), \quad \frac{\sigma_{22}}{\sigma_0} = 1$$

$$\Rightarrow \frac{\tau}{\sigma_0}(\xi_1) = \frac{1}{2} (\xi_1^2 - 1) \sin 2\varphi - \xi_1 \cos 2\varphi$$

$$0 = \frac{d\tau}{d\xi_1} = \xi_1 \sin 2\varphi - \cos 2\varphi \Rightarrow \underline{\xi_1 = \cot 2\varphi}$$

3
a

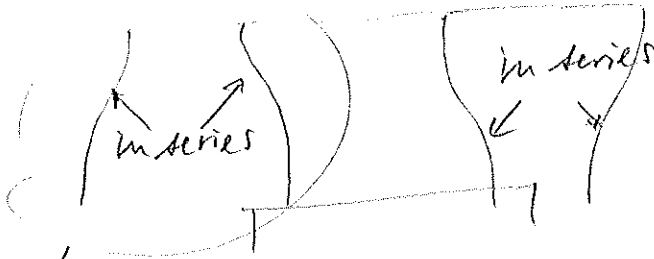


$$\text{end rotation} = 0 = \frac{Fb^2}{2EI} - \frac{Mb}{EI} \Rightarrow M = \frac{1}{2} Fb$$

$$\text{end deflection } u = \frac{Fb^3}{3EI} - \frac{Mb^2}{2EI} = \left(\frac{1}{3} - \frac{1}{4}\right) \frac{Fb^3}{EI} = \frac{Fb^3}{12EI}$$

$$k_1 = F/u = \frac{12EI}{b^3}, \quad I = \frac{1}{12} dt^3 \rightarrow k_1 = Ed \left(\frac{t}{b}\right)^3$$

b



$$\frac{1}{k_2} = \frac{1}{k_1} + \frac{1}{k_1} = \frac{2}{k_1} \Rightarrow k_2 = \frac{1}{2} k_1$$

$$\text{top stiffness} = k_2 + k_2 = k_1$$

$$\text{btm "}$$

$$k = 2k_1$$

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = \frac{1}{2\pi} \sqrt{\frac{24EI}{b^3} \frac{1}{\rho A d}}$$

$$= \frac{1}{2\pi} \sqrt{\frac{2E dt^3}{\rho A d b^3}} = \frac{1}{2\pi} \sqrt{\frac{2E}{\rho A} \left(\frac{t}{b}\right)^3}$$

$$\Rightarrow \frac{2E}{\rho A} \left(\frac{t}{b}\right)^3 = (2\pi f)^2 \Rightarrow \left(\frac{t}{b}\right)^3 = \frac{\rho A}{2E} (2\pi f)^2$$

$$t \approx 4.95 \times 10^{-3} b$$

$$= 0.99 \mu\text{m}$$

$$= \frac{2.3 \times 10^3 (\text{kg/m}^3)^{30} \times 10^4 \times 10^{-12} (\text{m}^2)}{224 \times 10^9 (\text{N/m}^2)}$$

$$= \frac{2.3 \times 10^3 (2\pi)^2 \times 10^{3+4-12+6}}{224 \times 10^9} \left(2\pi \cdot 10^3 / \text{s}\right)^2$$

$$= \frac{12.16}{10.73 \times 10^{-9}} = 121.6 \times 10^{-9}$$

←